

(december 2017)



[noForth website](#)

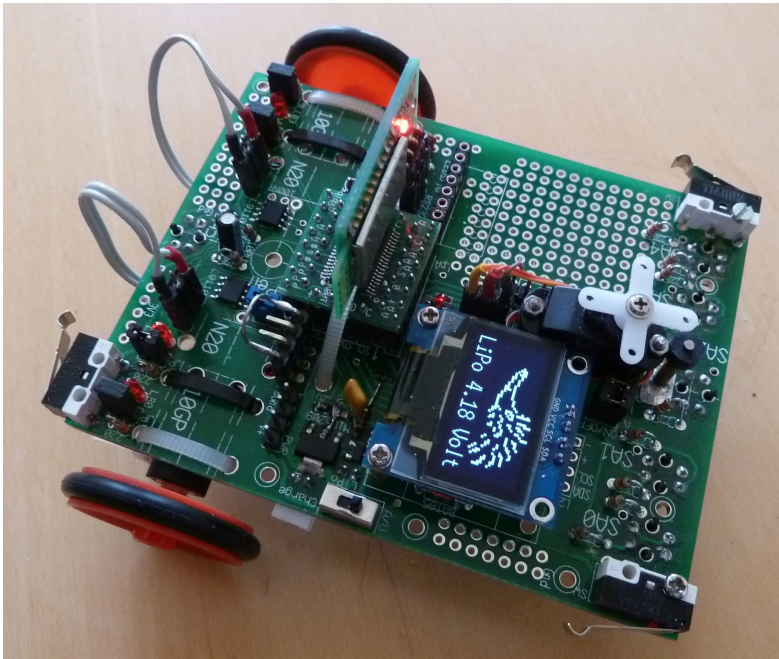
## **MSP430G2955 on Cosey robot with noForth 2955**

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In this text we refer to these three documents:

- SLAS800.PDF "MSP430G2x55 mixed signal microcontroller"
- SLAU144J.PDF "MSP430x2xx Family User's Guide"

# 1. Cosey robot with noForth 2955



Cosey robot vsn-00, Core Sub-Architecture: MSP430  
Parts: Two printed circuits and all components,  
Bluetooth module, Building instructions

- May be ordered at HCC Forth gg

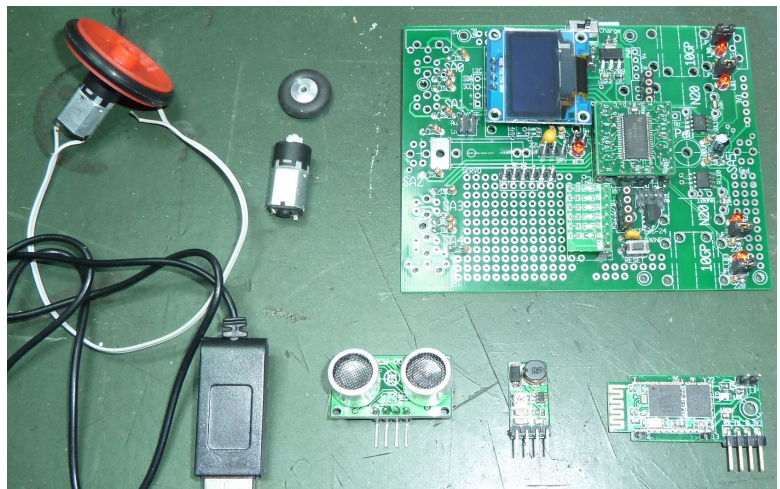
## RS232/USB driver

The USB chip on the mini-v3 board is the PL2303hx. This Prolific USB-chip needs a specific driver under Windows. Unzip [this file](#) and execute "PL2303\_Prolific\_DriverInstaller\_v1.11.0.exe".

Windows 8 and higher no longer supports the PL2303hx USB-chip. If you have a modern Windows a communication module with an PL2303TA chip could be a solution.



The connector uses a MSP430F5529 Launchpad as programmer with a simple four wire cable. An other way is using MSPdebug and a MSP430G2 Launchpad.



Parts of the Cosey robot

## i/o port connections on Cosey robot

### Port 1

Digital i/o, BSL

P1.0 Switch left  
P1.1 Bootloader TX  
P1.2 Motor A  
P1.3 Switch right  
P1.4 Switch back  
P1.5 Motor A  
P1.6 Motor B  
P1.7 Motor B

### Port 2

Digital i/o, BSL, analog

P2.0 Analog 0  
P2.1 Analog 1  
P2.2 Bootloader RX  
P2.3 Analog 3  
P2.4 Analog 4  
P2.5 I04  
P2.6 Servo  
P2.7 I05

### Port 3

Digital i/o, UART, analog

P3.0 Analog 5  
P3.1 SDA  
P3.2 SCL  
P3.3 I00  
P3.4 Uart TX  
P3.5 Uart RX  
P3.6 Led 1  
P3.7 Led 0

### Port 4

Digital i/o, analog

P4.0 I02  
P4.1 I03  
P4.2 I01  
P4.3 LiPo analog in  
P4.4 Analog 13  
P4.5 Led 3  
P4.6 Led 2  
P4.7 Shutdown

## Connectors on Cosey robot

Charge = LiPo charge connector  
LiPo = One cell Lipo battery connector  
PWR = V+ & GND  
BOOST = Optional voltage doubler for DC motors  
A0 = Analog power on/off for sensor  
5 x JP = Led output connectors  
BSL = MSP programming connector  
RS232 = Bluetooth/RS232 connector  
LEDS/I0 = Ledboard or I/O connector  
RS232/BT = Bluetooth transceiver connector  
SRV = Servo connector  
VL53L0X = Lidar connector  
ON/OFF = Front sensor power on/off  
OLED = SSD1306 oled display connector

## Hardware on Cosey robot

- Five Red leds
- Three switches
- Six floor sensors
- Two DC motors
- One micro servo
- One Lidar or US-sensor
- LiPo battery measurement circuit
- 128 kByte FRAM or EEPROM
- Reset switch

## 2. MSP430G2955 i/o ports

### Port addresses

The MSP430G2955 port registers are memory mapped. An overview:

<u>Label</u>	<u>P1</u>	<u>P2</u>	<u>P3</u>	<u>P4</u>	<u>Function</u>
PxIN	20	28	18	1C	In
PxOUT	21	29	19	1D	Out
PxDIR	22	2A	1A	1E	Direction
PxIFG	23	2B			Interrupt flag
PxIES	24	2C			Interrupt edge on
PxIE	25	2D			Interrupt on
PxSEL	26	2E	1B	1F	Select
PxREN	27	2F	10	11	Resistor on/off
PxSEL2	41	42	43	44	Select 2

See: SLAS800.PDF under "peripheral file map", from page 16-18.

### PxDir, PxREN and PxOUT

The three registers PxDIR, PxREN and PxOUT are used to configure an i/o pin:

<u>PxDIR</u>	<u>PxREN</u>	<u>PxOUT</u>	<u>Pin configuration</u>
0	0	x	Floating input
0	1	0	Input with resistor to GND
0	1	1	Input with resistor to VCC
1	x	x	Output

More info in SLAU144J.PDF page 328-329.

Texas Instruments recommends to configure unconnected i/o pins as Output.

### PxSEL and PxSEL2

The registers PxSEL and PxSEL2 are to assign a special function to an i/o pin. In this way, for example, the ADC or UART can be activated.

More info: SLAS800.PDF page 43-63: Port Pin Functions.

<u>PxSEL2</u>	<u>PxSEL</u>	<u>i/o-function</u>
0	0	Normal i/o
0	1	Basic extra function
1	0	Controller specific!
1	1	Second extra function

### 3. MSP430G2955 RAM & ROM

RAM            1100 - 20FF  
FlashROM      2100 - FFFF

### 4. MSP430G2955 Interrupt vectors

FFDE      End of free Flash

FFE0      Timer A1 CCR1 CCR2  
FFE2      Timer A1 CCR0  
FFE4      P1  
FFE6      P2  
FFE8      ...  
FFEA      ADC  
FFEC      USCI B0 TX  
FFEE      USCI B0 RX

FFF0      TIMER A0 CCR1 CCR2  
FFF2      TIMER A0 CCR0  
FFF4      WATCHDOG  
FFF6      COMPARATOR  
FFF8      TIMER B0 CCR1 CCR2  
FFFA      TIMER B0 CCR0  
FFFC      NMI  
FFFE      RESET

See SLAS800.PDF page 9 for details.

### 5. Processor registers in noForth

All processor registers (R0..R15) have their own name in noForth assembler:

PC	RP (SP in TI texts!)	SR	CG	MSP430 system registers	
SP	IP	TOS	DOX	NXT	noForth system registers
W	DAY	SUN	MOON		Registers, locally used by noForth
XX	YY	ZZ			Unused (free) registers

